

“Information technology has been praised as a labor saver and cursed as a destroyer of obsolete jobs. But the entire edifice of modern computing rests on a fundamental irony: **the software that makes it all possible is, in a very real sense, handmade.** Every miraculous thing computers can accomplish begins with a human programmer entering lines of code by hand, character by character.”

— Moshe Y. Vardi

An Introduction to Program Synthesis

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An example: Flash Fill in Excel 2013

The image displays two screenshots of Microsoft Excel 2013 illustrating the Flash Fill feature. The left screenshot shows a list of 11 Social Security Numbers (SSNs) in column A. The right screenshot shows the same list with column B filled with the formatted SSNs (e.g., 542-36-8978).

SSN	Column2
542368978	542-36-8978
123145542	123-14-5542
121247543	121-24-7543
454545465	454-54-5465
642548745	642-54-8745
514852145	514-85-2145
152358834	152-35-8834
642974682	642-97-4682
465859673	465-85-9673
367593684	367-59-3684

Flash Fill

An example: Flash Fill in Excel 2013

	A	B
1	Names	Initials
2	Neil Lieber	N L
3	Mathew Prisco	
4	Althea Bertin	
5	Kelly Gamblin	
6	Chandra Valenzula	
7	Cody Castillon	
8	Tyrone Brazier	
9	Althea Buhl	
10	Dollie Munsey	
11	Allyson Phou	

	A	B
1	Names	Initials
2	Neil Lieber	N L ↕
3	Mathew Prisco	M P
4	Althea Bertin	A B
5	Kelly Gamblin	K G
6	Chandra Valenzula	C V
7	Cody Castillon	C C
8	Tyrone Brazier	T B
9	Althea Buhl	A B
10	Dollie Munsey	D M
11	Allyson Phou	A P
12		

Flash Fill

An example: Flash Fill in Excel 2013

	Column1	Column2
2	[CPT-00350	[CPT-00350]
3	[CPT-00340	
4	[CPT-11536	
5	[CPT-11222	
6	[CPT-115]	
7	[CPT-1153622]	
8	[CPT-00340]	
9	[CPT-11536]	
10	[CPT-11222]	
11	[CPT-115	
12	[CPT-1163	

Add a ']'

Some ']' are missing

An example: Flash Fill in Excel 2013

	Column1	Column2
2	[CPT-00350	[CPT-00350]
3	[CPT-00340	[CPT-00340]
4	[CPT-11536	[CPT-11536]
5	[CPT-11222	[CPT-11222]
6	[CPT-115]	[CPT-115]
7	[CPT-1153622]	[CPT-1153622]
8	[CPT-00340]	[CPT-00340]
9	[CPT-11536]	[CPT-11536]
10	[CPT-11222]	[CPT-11222]
11	[CPT-115	[CPT-115]
12	[CPT-1163	[CPT-1163]

Too many!

An example: Flash Fill in Excel 2013

	Column1	Column2
2	[CPT-00350	[CPT-00350]
3	[CPT-00340	[CPT-00340]
4	[CPT-11536	[CPT-11536]
5	[CPT-11222	[CPT-11222]
6	[CPT-115]	[CPT-115]
7	[CPT-1153622]	[CPT-1153622]]
8	[CPT-00340]	[CPT-00340]]
9	[CPT-11536]	[CPT-11536]]
10	[CPT-11222]	[CPT-11222]]
11	[CPT-115	[CPT-115]
12	[CPT-1163	[CPT-1163]

 Fix it

Then rerun Flash Fill

An example: Flash Fill in Excel 2013

	Column1	Column2
2	[CPT-00350	[CPT-00350]
3	[CPT-00340	[CPT-00340]
4	[CPT-11536	[CPT-11536]
5	[CPT-11222	[CPT-11222]
6	[CPT-115]	[CPT-115]
7	[CPT-1153622]	[CPT-1153622]
8	[CPT-00340]	[CPT-00340]
9	[CPT-11536]	[CPT-11536]
10	[CPT-11222]	[CPT-11222]
11	[CPT-115	[CPT-115]
12	[CPT-1163	[CPT-1163]

Correct!

What is Program Synthesis?

- **Program Synthesis** aims to **automate** (tedious part of) programming.
- A programmer only tells the computer **what he wants** (through **formal or informal specifications**), and leaves the details of **how** to the computer to figure out.
- **Flash Fill** is an instance of **Example-Driven** Program Synthesis (also called **Inductive Program Synthesis**)
- There is also another kind of program synthesis: **Deductive Program Synthesis** (usually using formal specifications)

The Leon Framework

- **Leon** is an automated system for **synthesizing** and **verifying** functional **Scala** programs, developed by EPFL
- **Leon** uses Scala constructs *require* and *ensuring* to document **preconditions** and **postconditions** of functions

```
def max(x: Int, y: Int): Int = {  
  val d = x - y  
  if (d > 0) x  
  else y  
} ensuring(res =>  
  x <= res && y <= res && (res == x || res == y))
```

The Leon Framework - Verification

- The code seems to work correctly. However, Leon automatically finds that it is not correct, showing us a counter-example inputs, such as

```
x -> -1639624704  
y -> 1879048192
```

- The problem is due to **overflow** of 32-bit integers!

```
def max(x: Int, y: Int): Int = {  
  val d = x - y  
  if (d > 0) x  
  else y  
} ensuring(res =>  
  x <= res && y <= res && (res == x || res == y))
```

The Leon Framework - Verification

- To use **unbounded integers**, we simply change the types to *BigInt*, obtaining a program that verifies (and, as expected, passes all the test cases)

```
def max(x: BigInt, y: BigInt): BigInt = {  
  val d = x - y  
  if (d > 0) x  
  else y  
} ensuring(res =>  
  x <= res && y <= res && (res == x || res == y))
```

The Leon Framework - Synthesis

- Leon can also **synthesize** programs from given specifications
- We omit the implementation of *max*, using only a placeholder `???[BigInt]` indicating we are looking for an unknown implementation of an integer type

```
def max(x: BigInt, y: BigInt): BigInt = {  
  ???[BigInt]  
} ensuring(res =>  
  x <= res && y <= res && (res == x || res == y))
```

- Leon can then automatically generate an implementation that satisfies this specification, such as

```
if (x <= y) x  
else y
```

The Escher Algorithm

Synthesizing recursive programs

The *Escher* Algorithm

- An **example-driven** synthesis algorithm aims to synthesize **recursive programs**
- Uses a very simple target language (only **argument variable**, **if-then-else statement** and **function application**)
- Initially described in the CAV'13 paper *Recursive Program Synthesis*
- I'm going to introduce a **modified version** of this algorithm called *Escher-Scala* (the project I'm currently working on)

An *Escher-Scala* Example

- Suppose we want to synthesize a **list reverse** function
- First, we need to provide a **function signature**

```
reverse(xs: List['0]): List['0]
```

- Haskell equivalent:

```
reverse :: List t0 -> List t0  
reverse xs = ...
```

An *Escher-Scala* Example

- Then we provide some **input-output examples**

```
Initial Examples (3):  
([1]) -> []  
([1, 2]) -> [2, 1]  
([1, 2, 3]) -> [3, 2, 1]
```

- During the synthesis, the algorithm also asks results for some **additional input cases**, we say this algorithm uses an **Oracle**.

```
Additional examples provided (9):  
([2, 3]) -> [3, 2]  
([2]) -> [2]  
([1, 1]) -> [1, 1]  
([3, 3]) -> [3, 3]  
([1]) -> [1]  
([3]) -> [3]  
([3, 2]) -> [2, 3]  
([1, 3]) -> [3, 1]  
... (1 more not shown) ...
```

An *Escher-Scala* Example

- The program *Escher-Scala* found:

```
Program found:
```

```
reverse(@xs: List['0']): List['0] =  
  if isNil(@xs)  
  then @xs  
  else concat(reverse(tail(@xs)), cons(head(@xs), nil()))
```

- Haskell equivalent:

```
reverse xs =  
  if xs == []  
  then xs  
  else reverse (tail xs) ++ (head xs : [])
```

An *Escher-Scala* Example

- The program *Escher-Scala* found:

```
Program found:
```

```
reverse(@xs: List['0']): List['0] =  
  if isNil(@xs)  
  then @xs  
  else concat(reverse(tail(@xs)), cons(head(@xs), nil()))
```

- It took the algorithm only **219ms** to find this example

An *Escher-Scala* Example

- The program Escher-Scala found:

```
Program found:
```

```
reverse(@xs: List['0']): List['0] =  
  if isNil(@xs)  
  then @xs  
  else concat(reverse(tail(@xs)), cons(head(@xs), nil()))
```

- It took the algorithm only **219ms** to find this example
- Actually, for easy testing, instead of manually type in those **Oracle inputs**, I used **reference implementations**

The Component Set

- You probably have noticed that Escher used some **library functions** (**Components**) in the previous example:

isNil, head, tail, concat ...

- Escher always works under a **Component Set** — it only uses **components** (library functions) from this Component Set to synthesize programs.
- The Component Set is not fixed, they can be customized for different synthesis tasks

The Standard Component Set

- All the following synthesis tasks were tested under a **standard Component Set** (26 components), possibly with additional components.

```
// boolean  
T, F, and, or, not, equal, isNil, isNonNeg,  
// list  
head, tail, cons, concat, nil,  
// integer  
zero, inc, dec, neg, length, plus, div2
```

```
//binary tree  
createLeaf, createNode, isLeaf, treeValue, treeLeft, treeRight
```

The Standard Component Set

- It is also quite easy to implement **new components** and **data types** in Escher-Scala

```
case object TPair extends TypeConstructor {  
  val name: String = "Pair"  
  
  val arity: Int = 2  
}
```

```
case class ValueTree(value: BinaryTree[TermValue]) extends TermValue {  
  override def matchTypeAux(ty: Type, freeId: () => Int): Option[TypeSubst] = {...}  
  
  override def show: String = {...}  
  
  val sizeCompare: PartialFunction[TermValue, Boolean] = {...}  
}
```

More than reverse

- *Escher-Scala* can also synthesize many other interesting programs!
- **fib**: Fibonacci numbers

```
fib(@n: Int): Int =  
  if isNonNeg(inc(neg(@n)))  
  then inc(zero())  
  else plus(fib(dec(@n)), fib(dec(dec(@n))))
```

```
fib n =  
  if (-n+1) >= 0      -- n <= 1  
  then 1  
  else fib (n-1) + fib (n-2)
```

Initial Example

```
(0) -> 1  
(1) -> 1  
(2) -> 2  
(-3) -> 1  
(3) -> 3  
(4) -> 5  
(5) -> 8  
(6) -> 13
```

Additional examples

```
(-2) -> 1  
(-5) -> 1  
(-1) -> 1  
(-4) -> 1
```

More than reverse

- *Escher-Scala* can also synthesize many other interesting programs!
- **nodesAtLevel**: All nodes of a binary tree at some depth

```
nodesAtLevel(@tree: Tree['0'], @level: Int): List['0] =
  if or(isLeaf(@tree), not(isNonNeg(@level)))
  then nil()
  else if isNonNeg(neg(@level))
    then cons(treeValue(@tree), nil())
    else concat(nodesAtLevel(treeLeft(@tree), dec(@level)),
nodesAtLevel(treeRight(@tree), dec(@level)))
```

Contains and Dedup

- o **contains**: Whether an element is in a list

```
contains(@xs: List['0'], @x: '0'): Bool =  
  if isNil(@xs)  
  then F()  
  else if equal(@x, head(@xs))  
  then T()  
  else contains(tail(@xs), @x)
```

- o **dedup**: Remove all duplicate elements of a list

```
dedup(@xs: List['0']): List['0] =  
  if isNil(@xs)  
  then @xs  
  else if contains(tail(@xs), head(@xs))  
  then dedup(tail(@xs))  
  else cons(head(@xs), dedup(tail(@xs)))
```

Cartesian Product

- **cartesian**: Cartesian Product of two lists
- Example Set:

```
Initial Examples (4):  
([], [2, 3, 4]) -> []  
([5], []) -> []  
([5], [7, 8, 9]) -> [(5, 7), (5, 8), (5, 9)]  
([2, 3], [4, 5]) -> [(2, 4), (2, 5), (3, 4), (3, 5)]
```

Cartesian Product in detail

- The program Escher-Scala found:

```
cartesian(@xs: List['0], @ys: List['1]): List[Pair['0,'1]] =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else if isNil(tail(@xs))  
    then cons(createPair(head(@xs), head(@ys)), cartesian(@xs, tail(@ys)))  
    else concat(cartesian(cons(head(@xs), nil()), @ys), cartesian(tail(@xs), @ys))
```

- Rewrite it into a more readable form:

```
cartesian :: List t0 -> List t1 -> List (t0, t1)  
cartesian xs ys =  
  if xs == [] || ys == []  
  then []  
  else if tail xs == []  
    then (head xs, head ys) : cartesian xs (tail ys)  
    else cartesian [head xs] ys ++ cartesian (tail xs) ys
```

- We will come back to this example in later discussions

How it works

- Now, let me introduce the algorithm in detail
- Remember our synthesis is example-driven
- I'm going to use the list `length` example
- Function signature: `length(xs: List['0']): Int`
- Input-output examples:

```
([]) -> 0  
([1]) -> 1  
([2,3,4]) -> 3
```

What we want

- **Basic Objective:** Give the 3 input-output examples, we want to find a recursive program that passes all of them

- We can represent the 3 inputs as an **input vector**

$\{([], [1]), ([2, 3, 4])\}$

- Since we have only one value for each input:

$\{[], [1], [2, 3, 4]\}$

- We also represent our desired outputs as **output vector**

$\{0, 1, 3\}$

Terms

- Function signature: `length(@xs: List['0']): Int`
- Using only **components** and **input variables** (`@xs` in this example), we can write down a series of **terms** (expressions with valid types), each term has a corresponding **output vector**

```
zero() ~> {0,0,0}
@xs ~> {[], [1], [2,3,4]}
inc(zero()) ~> {1,1,1}
tail(@xs) ~> {Err, [], [3,4]}
isNil(@xs) ~> {T,F,F}
length(tail(@xs)) ~> {Err,0,2}
... ..
```

A diagram with two arrows. A blue arrow points from the 'Err' value in the output vector of the 'tail(@xs)' term to the 'Err' value in the output vector of the 'length(tail(@xs))' term. A red arrow points from the 'Err' value in the output vector of the 'length(tail(@xs))' term to the 'Err' value in the output vector of the 'length(tail(@xs))' term.

- Note that we also treat **length** as a **special component**, to calculate its output vector, the algorithm needs to ask **Oracle** for additional inputs.

Target Program

- If we can find a term with the desired output vector, then we are done!
- Otherwise, we may need to combine those terms into **programs**
- **Programs** are either **terms** or **if-then-else** expressions with the following shape:

```
if term1 then term2
else if term3 then term4
else if term5 then term6
... ..
else termN
```

- Or inductively: $P := \text{term}$
| if term then term else P

What we really want

- We can always find some “trivial programs” that pass all examples, for our `length` example:

```
if isNil(@xs) then zero()  
else if isNil(tail(@xs)) then inc(zero())  
else inc(inc(inc(zero()))))
```

- But the above program is not general enough! It will fail on other inputs like `[1,2]`
- What we really want is programs like this:

```
if isNil(@xs) then zero()  
else inc(length(tail(@xs)))
```

- How to avoid finding those “trivial” programs?
- **Observation:** The correct program is much simpler!

Guiding Heuristic

Occam's Razor

Among competing hypothesis, the one with the fewest assumptions should be selected.



Guiding Heuristic

- **Occam's Razor**: Among competing hypothesis, the one with the fewest assumptions should be selected.
- If there are multiple programs that pass the example set, the algorithm should return the “**simplest**” one.
- How to define the simpleness of a program? There is not any mathematically rigorous answer to this question yet.
- But experiment results demonstrate that the **size** (number of nodes in AST) of target programs is a good choice.

```
if isNil(@xs) then zero()  
else inc(length(tail(@xs)))
```

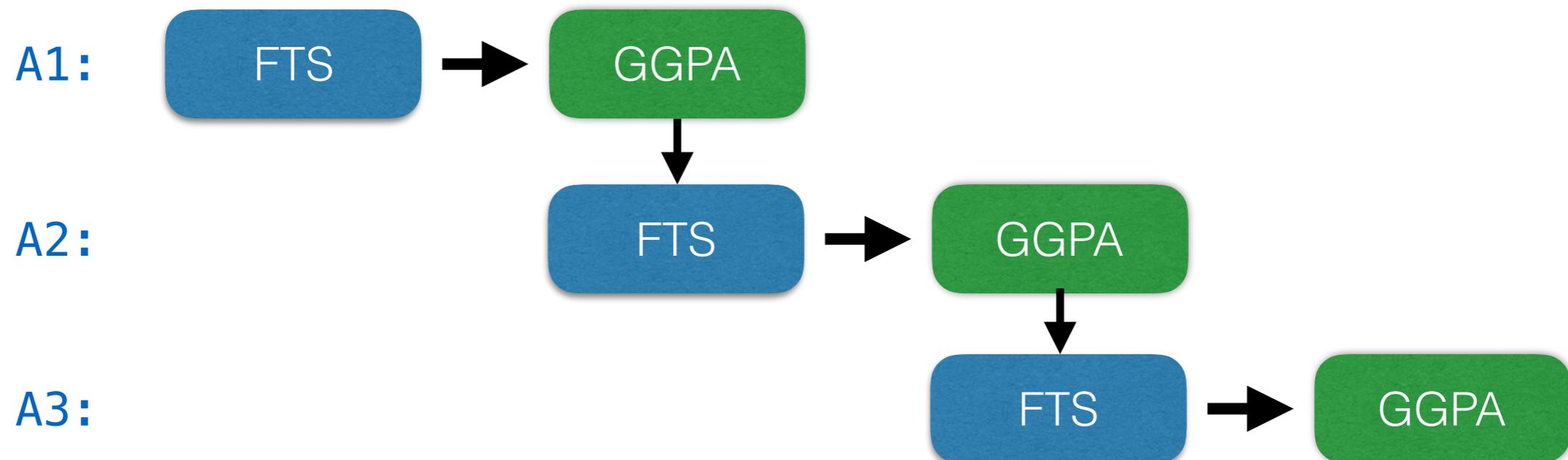
Size = 8

```
if isNil(@xs) then zero()  
else if isNil(tail(@xs)) then inc(zero())  
else inc(inc(inc(zero())))
```

Size = 14

Algorithm Overview

- The Escher-Scala algorithm consists of two **alternating** stages: **Forward Term Search (FTS)** and **Goal-Guided Program Assembly (GGPA)**
- In the n th **alternation**, the algorithm first find out all terms of size n (FTS), and then tries to assemble a correct target program using GGPA.



Forward Term Search

- If we want to synthesize term of size S , given a component that takes A arguments (arity = A), FTS searches for A terms whose sizes sum to $S-1$
- In our `length` example, at `alternation 4`, FTS can find all terms we need in order to synthesize a correct target program, along with many other terms:

```
zero() ~> {0,0,0}           size=1
isNil(@xs) ~> {T,F,F}       size=2
inc(length(tail(@xs))) ~> {Err,1,3} size=4
```

Observational Equivalence

- We can't just naively enumerate all possible terms; otherwise there will be too many of them!
- Many **syntactically different** terms are actually **equivalent in semantics** (have same meaning), **we only need the simplest one.**
- We can use **Observational Equivalence** as an approximation to semantical equivalence.

`{0,0,0}`

`zero()`

`dec(inc(zero))`

`plus(zero(),zero())`

`.. ..`

`{T,F,F}`

`isNil(@xs)`

`not(not(isNil(@xs)))`

`equals(T(),isNil(@xs))`

`.. ..`

Goal-Guided Program Assembly

- Main idea: If we can't find a term to satisfy a goal, we can **split** the goal using **if-then-else** expressions

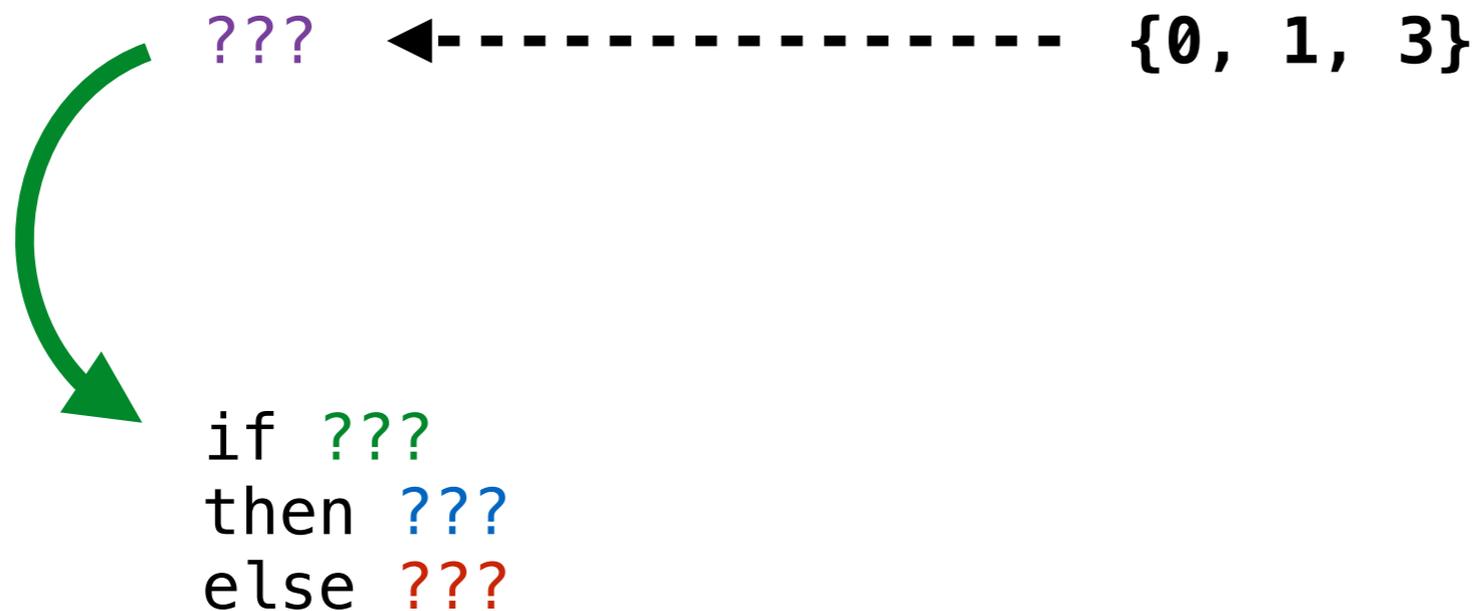
???



←----- {0, 1, 3}

Goal-Guided Program Assembly

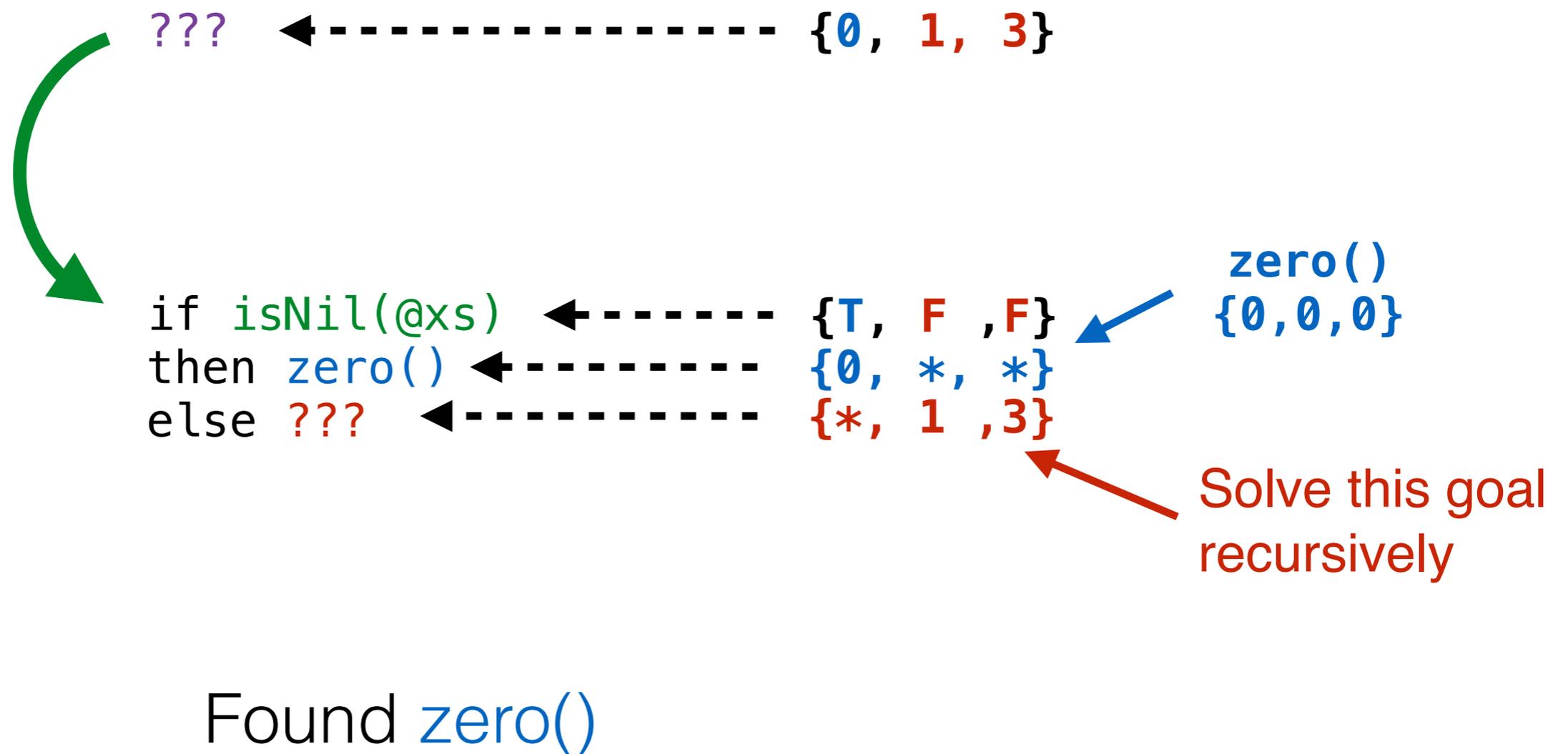
- Main idea: If we can't find a term to satisfy a goal, we can **split** the goal using **if-then-else** expressions



Now try to fill these 3 holes

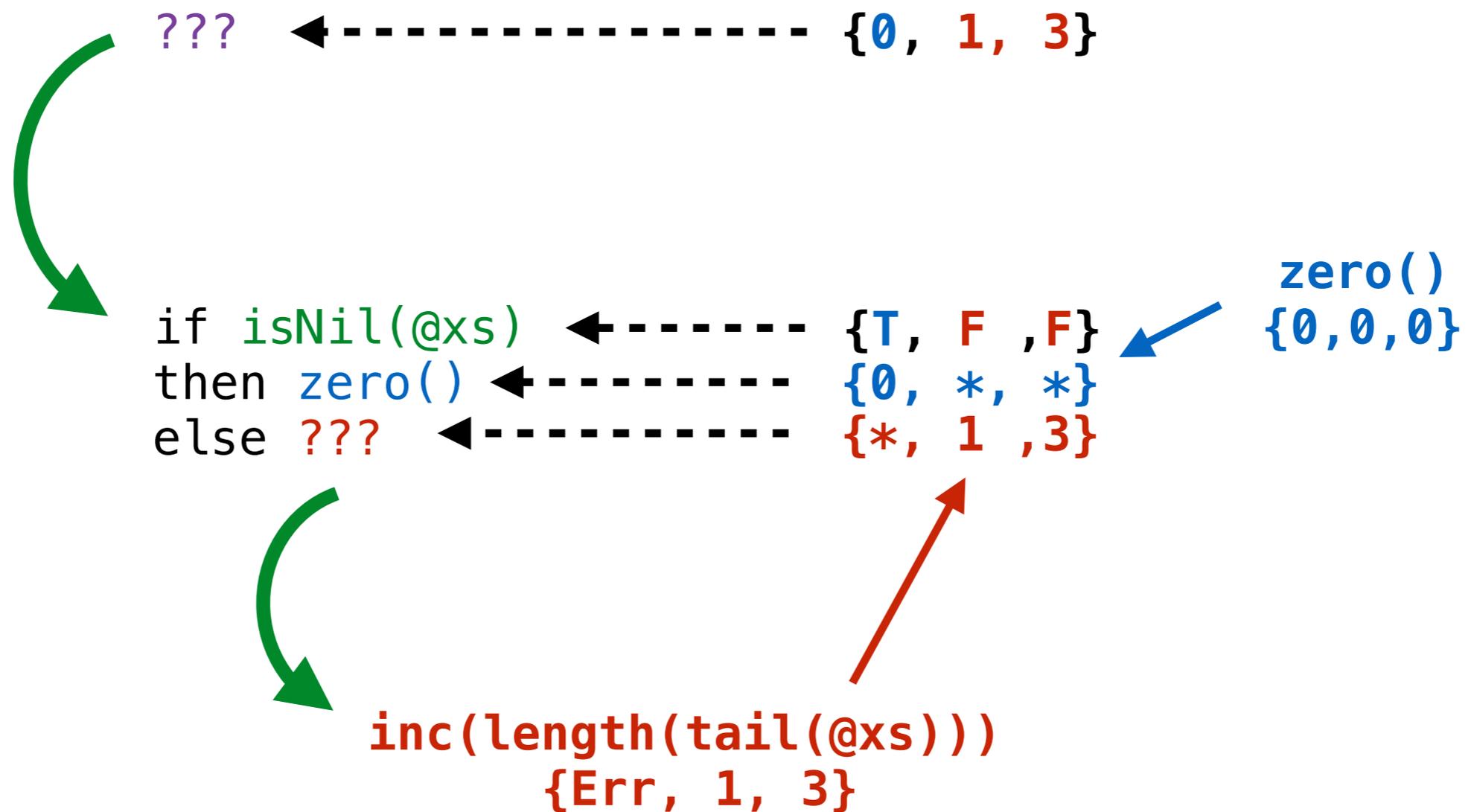
Goal-Guided Program Assembly

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Goal-Guided Program Assembly

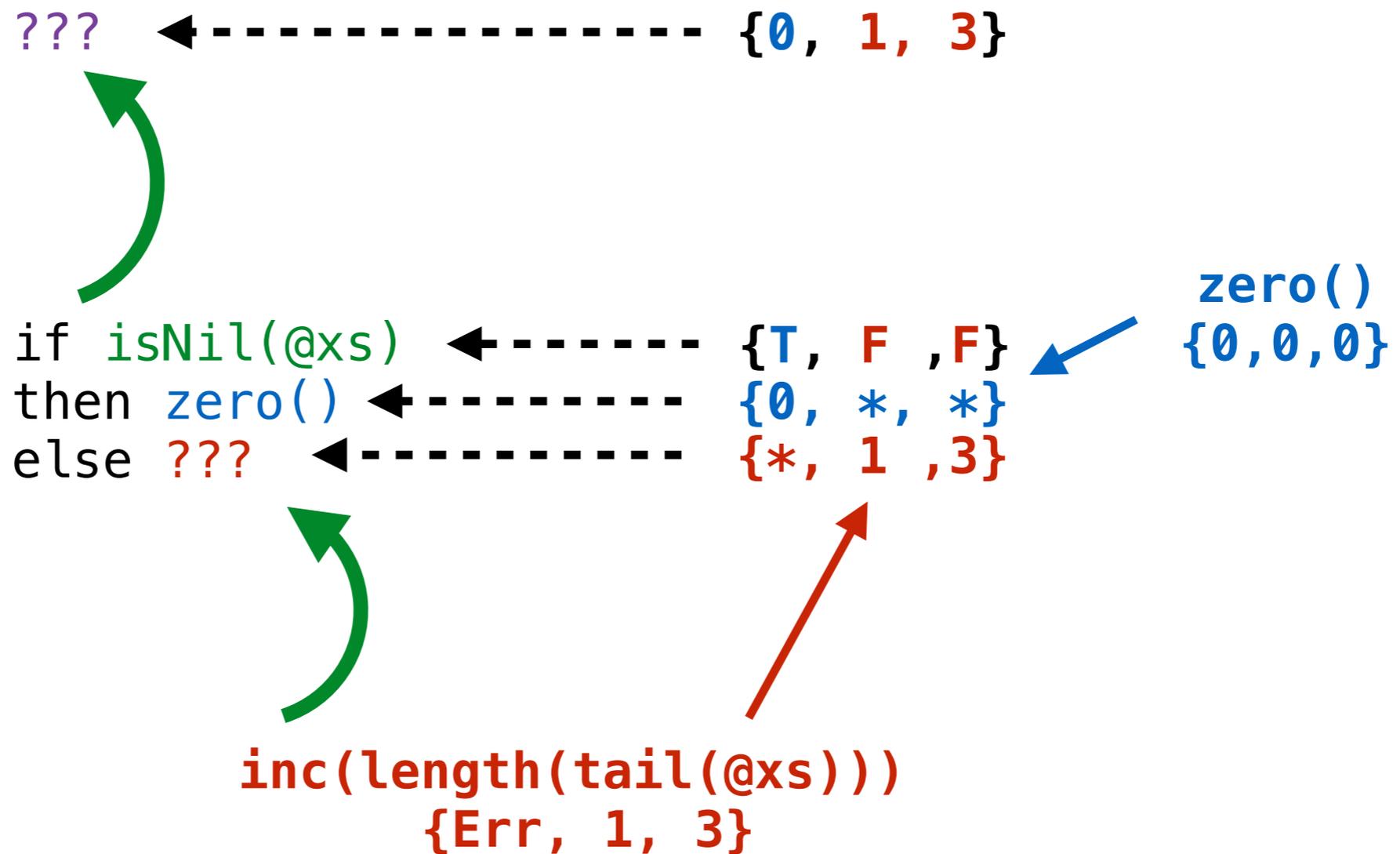
- Main idea: If we can't find a term to satisfy a goal, we can **split** the goal using **if-then-else** expressions



Recursively solved

Goal-Guided Program Assembly

- Main idea: If we can't find a term to satisfy a goal, we can **split** the goal using **if-then-else** expressions



Program Found!

Goal-Guided Program Assembly

- Main idea: If we can't find a term to satisfy a goal, we can **split** the goal using **if-then-else** expressions

- Result:

```
length(@xs)=  
  if isNil(@xs)  
  then zero()  
  else inc(length(tail(@xs)))
```

Avoid Non-terminating programs

- What if the algorithm find terms like this:

`length(@xs) ~> {0, 1, 3}`

- Note that this term has the exact output vector we want. But the resulting program **will not terminate!**

`length(@xs) =
length(@xs)`

- There always exists some non-terminating programs that are simpler than the correct, terminating ones!
- To avoid problems like this, Escher requires the **argument list** of recursive calls must be **“smaller”** than the **previous argument list**.

Termination Guarantee

- Intuition: If every time the program calls its self, the **size** of its argument list becomes **smaller**, then eventually, its argument list cannot be smaller anymore, thus the program terminates.

```
length([2,3,4])  
inc(length([3,4]))  
inc(inc(length([4])))  
inc(inc(inc(length([]))))  
inc(inc(inc(0)))
```



3

Termination Guarantee

- Intuition: If every time the program calls itself, the **size** of its argument list becomes **smaller**, then eventually, its argument list cannot be smaller anymore, thus the program terminates.
- To achieve this, we should be able to **compare** the size of two **values** of the same **data type**. And for each **data type**, there must exist some **smallest element**.
- For **integer**, we can define the size as its **absolute value**.
- For **lists**, we define the size as its **length**.
- Then we can define the usual **alphabetic order** on argument lists.

Check recursive calls

- In our `length` example, remember we have `input vector`:

`@xs ~> {[], [1], [2,3,4]}`

- For term `@xs`, if we apply `length` on it, because those three argument lists are the same as the `input vector` (thus not smaller than it), this results in 3 **Errs**:

`length(@xs) ~> {Err, Err, Err}`

- For term `tail(@xs)`

`tail(@xs) ~> {Err, [], [3,4]}`

Check recursive calls

- In our `length` example, remember we have `input vector`:

`@xs ~> {[], [1], [2,3,4]}`

- For term `@xs`, if we apply `length` on it, because those three argument lists are the same as the `input vector` (thus not smaller than it), this results in 3 **Errs**:

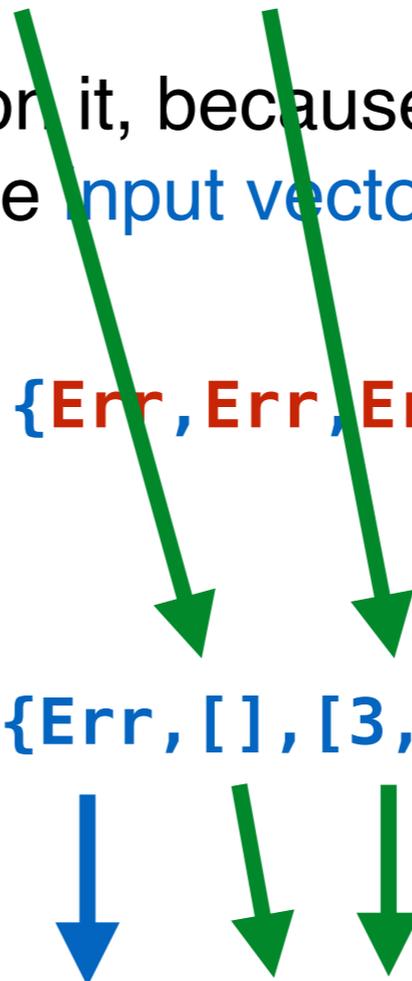
`length(@xs) ~> {Err, Err, Err}`

- For term `tail(@xs)`

`tail(@xs) ~> {Err, [], [3,4]}`

`length(tail(@xs)) ~> {Err, 0, 2}`

decreasing



Rebooting

- After our algorithm has found a recursive program, we are not done yet. We must check whether it works correctly on those additional recursive calls we encountered during the synthesis.
- Why? Because during the Goal-Guided Program Assembly stage, we may have used the output vector of some recursive terms

$\text{length}(\{\text{Err}, [], [3,4]\}) \rightsquigarrow \{\text{Err}, 0, 2\}$

- But GGPA only guarantee to find a program that satisfies the original input-output examples

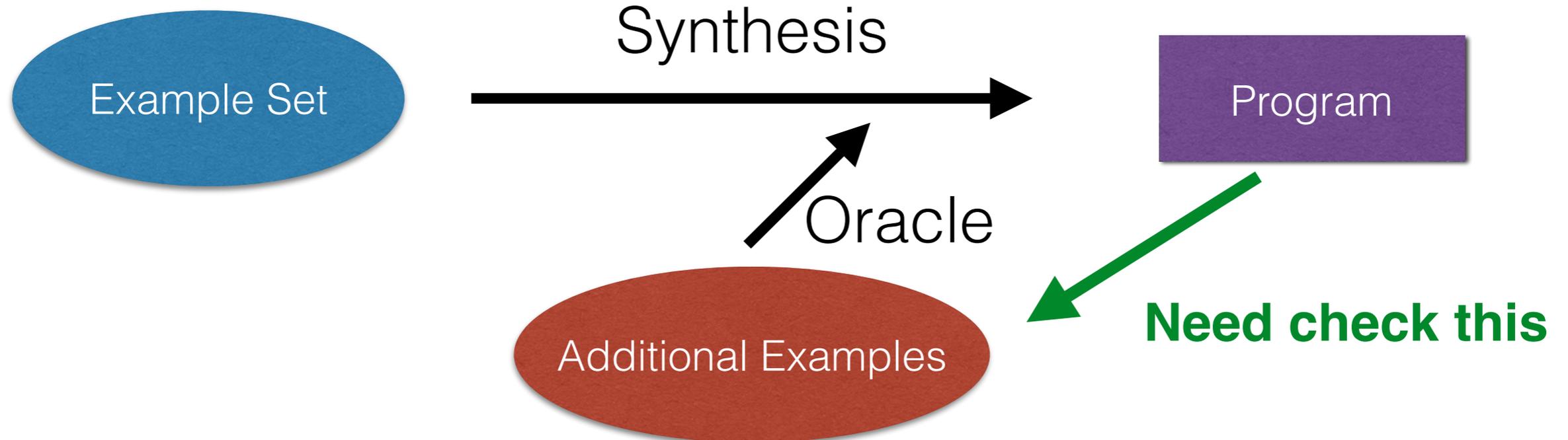
$\text{length}(\{[], [1], [2,3,4]\}) \rightsquigarrow \{0, 1, 3\}$

- The resulting program may not satisfy those additional examples:

$\text{length}([3,4]) =??= 2$

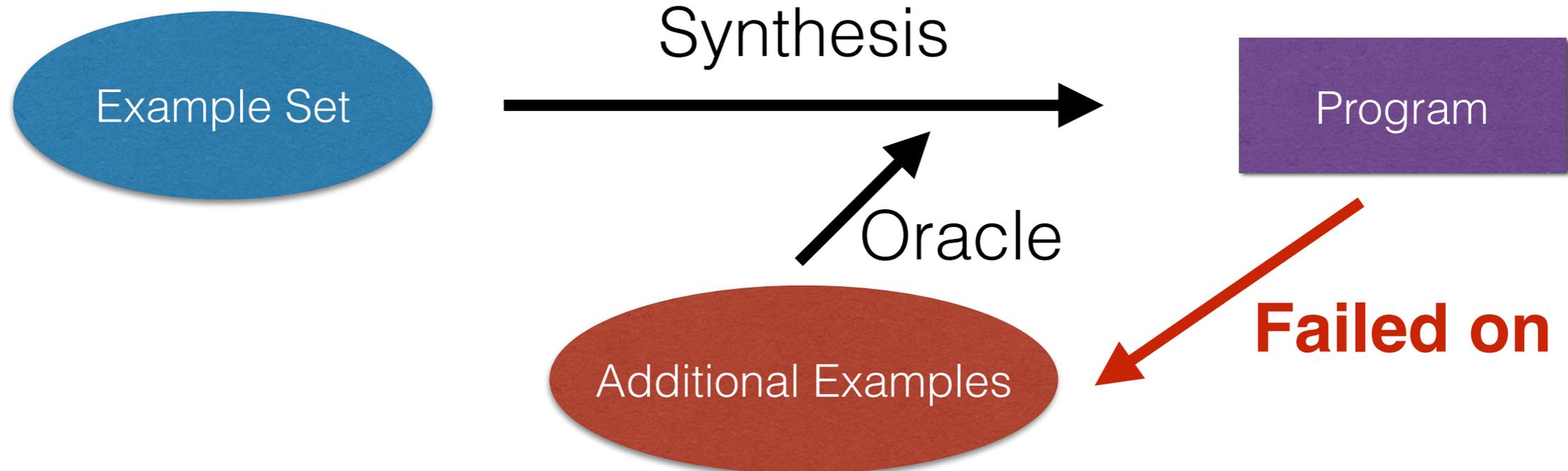
Rebooting, continued

- But the correctness of GGPA relies on the output vector of these recursive terms. So we must check that the algorithm we get is actually correct on these additional examples.



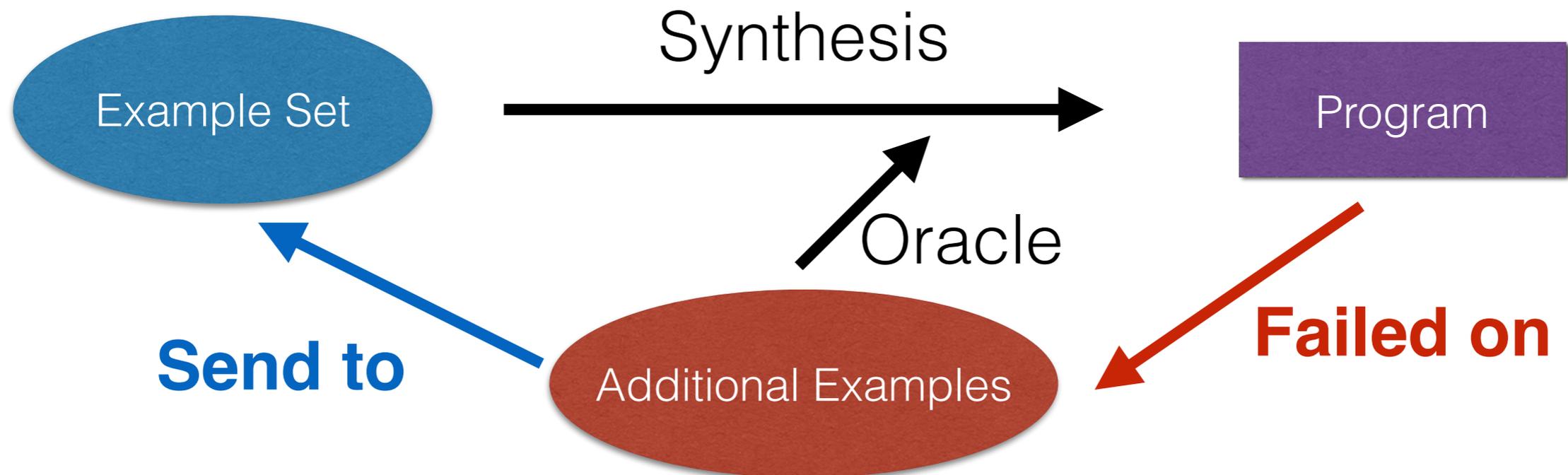
Rebooting, continued

- But the correctness of GGPA relies on the output vector of these recursive terms. So we must check that the algorithm we get is actually correct on these additional examples.
- What if the found program failed on some additional examples?



Rebooting, continued

- But the correctness of GGPA relies on the output vector of these recursive terms. So we must check that the algorithm we get is actually correct on these additional examples.
- What if the found program failed on some additional examples?
- In this case, the program must be wrong and we add those failed examples into the example set and reboot the algorithm. This is called **rebooting**.



Rebooting, continued

- But the correctness of GGPA relies on the output vector of these recursive terms. So we must check that the algorithm we get is actually correct on these additional examples.
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- In this case, the program must be wrong and we add those failed examples into the example set and reboot the algorithm. This is called **rebooting**.



Benchmark

- Problem: **Too many** examples required!

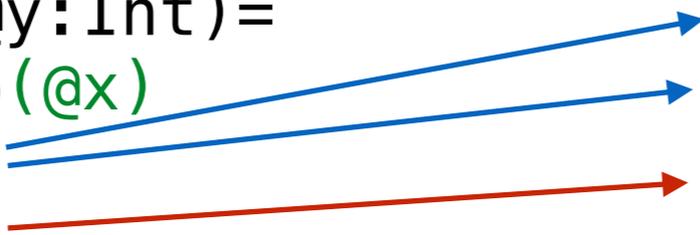
Summary:

name	cost	depth	examples	reboots	time
reverse	12	8	2/10	None	279.58ms
stutter	13	9	3/10	None	129.90ms
cartesian	32	12	4/78	None	502.89ms
squareList	14	9	6/2	None	538.35ms
fib	15	8	8/4	None	344.94ms
insert	19	9	8/292	None	534.71ms
compress	25	9	8/22	None	36.98ms
nodesAtLevel	27	11	11/427	None	3,472.47ms
contains	14	5	7/22	None	4.58ms
dropLast	15	6	5/10	None	9.10ms
evens	16	7	5/20	None	10.68ms
dedup	46	16	16/149	7	103,932.40ms
tConcat	15	11	6/2213	None	12,057.56ms
Total time: 121.854s					

A New Algorithm

- I'm currently working on a new algorithm to address this problem
- The new algorithm is called **AscendRec** and it **does not require an Oracle** to work
- Basic idea: Instead of asking the Oracle, we try to **partially evaluate** the **output vector** of a recursive term during **GGPA**

```
f(@x:Int, @y:Int)=  
  if isZero(@x)  
  then @y  
  else ???
```



The diagram shows three arrows originating from the code on the left and pointing to the results on the right. Two blue arrows point from the 'then @y' line to the results 'f(0,1) = 1' and 'f(0,3) = 3'. One red arrow points from the 'else ???' line to the result 'f(1,2) = ?'.

<code>f(0,1)</code>	=	<code>1</code>
<code>f(0,3)</code>	=	<code>3</code>
<code>f(1,2)</code>	=	<code>?</code>

`f({(0,1), (0,3), (1,2)}) ~> {1, 3, ?}`

The Unknown Value

- In addition to **Err**, we need another special value, called **Unknown**, written as **'?'**
- Moreover, during **Forward Term Search**, we must distinguish recursive from non-recursive terms. An recursive term must have at least one **'?'**s in its output vector, **otherwise we treated it as if it's non-recursive**

```
@xs ~> {[], [1], [2,3,4]}
tail(@xs) ~> {Err, [], [3,4]}
isNil(@xs) ~> {T,F,F}
length(nil())
~> {0,0,0}
... ..
```

Non-recursive

```
length(tail(@xs)) ~> {Err, 0, ?}
inc(length(tail(@xs)))
~> {Err, 1, ?}
... ..
```

Recursive

Ascending-Recursive Form

- This new algorithm can only efficiently find programs of a special form — The target program should be **ascending-recursive**
- **Ascending-recursive Form (ARF)**: A **program** is said to be in **ARF** if:
 1. Its **first branch** and **condition expressions** are non-recursive

(suppose **length** is an recursive call)

```
if not(isNil(@xs))  
then inc(length(tail(@xs)))  
else zero()
```



```
if isNil(@xs)  
then zero()  
else inc(length(tail(@xs)))
```



Ascending-Recursive Form

- This new algorithm can only efficiently find programs of a special form — The target program should be **ascending-recursive**
- **Ascending-recursive Form (ARF)**: A **program** is said to be in **ARF** if:
 1. Its **first branch** and **condition expressions** are non-recursive
 2. If the program recursively calls itself in the **i** th branch, then in the following recursive evaluation, it can only access the **j** th branches where $1 \leq j \leq i$

```
cartesian :: List t0 -> List t1 -> List (t0, t1)
cartesian xs ys =
  if xs == [] || ys == []
  then []
  else if tail xs == []
  then (head xs, head ys) : cartesian xs (tail ys)
  else cartesian [head xs] ys ++ cartesian (tail xs) ys
```



1st branch

2nd branch

3rd branch

Ascending-Recursive Form

- This new algorithm can only efficiently find programs of a special form — The target program should be **ascending-recursive**
- **Ascending-recursive Form (ARF)**: A **program** is said to be in **ARF** if:
 1. Its **first branch** and **condition expressions** are non-recursive
 2. If the program recursively calls itself in the **i** th branch, then in the following recursive evaluation, it can only access the **j** th branches where $1 \leq j \leq i$
 3. Nested recursive calls are not allowed

(suppose **fib** is an recursive call)

`fib(fib(n-1))`



`fib(n-1)+fib(n-2)`



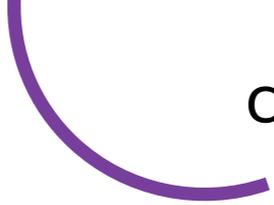
Partial Evaluation

- We are going to use the **cartesian** example to demonstrate how to efficiently search for **ascend-recursive** programs without using an **Oracle**.
- Remember **GGPA** is a top-down process — We start from an initial goal (**output vector**), and gradually split it using **if statements**

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], [1]), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{([], [1], [(5,7), (5,8), (5,9)]), ([2,4], [2,5], [3,4], [3,5])}`

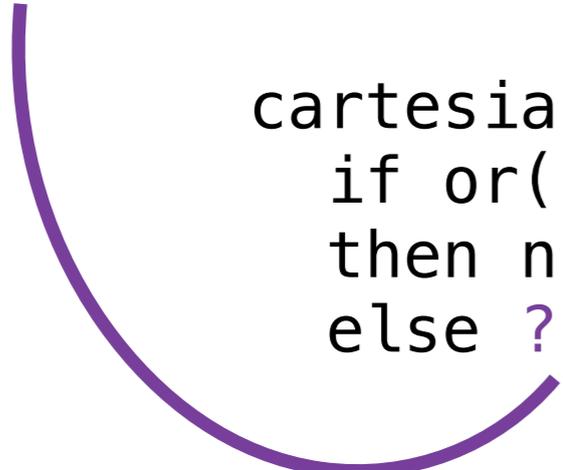
 `cartesian(@xs, @ys) =`
`???`

- Now try to split the goal. Because the first branch must be non-recursive, we split it just like before

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], [1]), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{* , * , [(5,7), (5,8), (5,9)], [(2,4), (2,5), (3,4), (3,5)]}`



```
cartesian(@xs, @ys) =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else ???
```

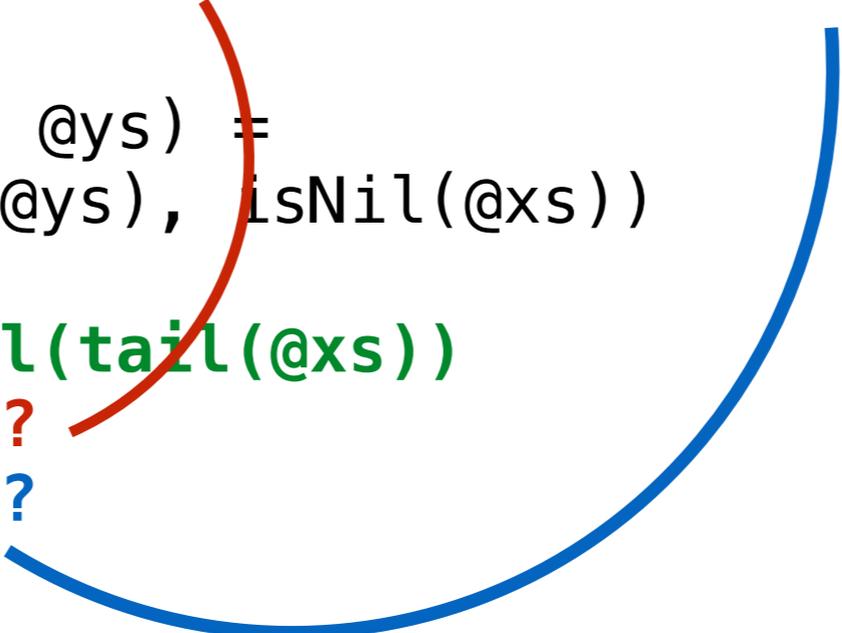
- The first two cases in the goal vector are solved
- Try to split again

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], []), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{* , * , [(5,7), (5,8), (5,9)], [(2,4), (2,5), (3,4), (3,5)]}`

```
cartesian(@xs, @ys) =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else if isNil(tail(@xs))  
        then ???  
        else ???
```



- Now we need to decide which term to put into the **red** hole
- Suppose we have tried all non-recursive terms and none of them can lead to a successful assembly
- Then the algorithm tries to find a recursive term

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], []), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{* , * , [(5,7), (5,8), (5,9)], [(2,4), (2,5), (3,4), (3,5)]}`

```
cartesian(@xs, @ys) =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else if isNil(tail(@xs))  
        then ???  
        else ???
```

- What's the output vector of the term below?

```
cons(createPair(head(@xs), head(@ys)), cartesian(@xs, tail(@ys)))
```

- Before GGPA, it is:

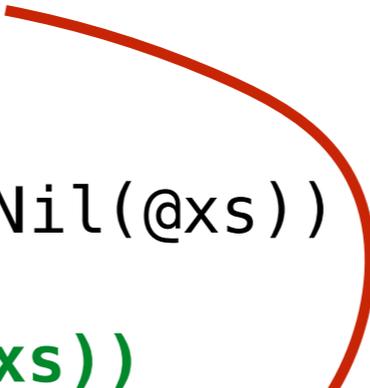
```
{?, Err, ?, ?}
```

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], [1]), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{* , * , [(5,7), (5,8), (5,9)], [(2,4), (2,5), (3,4), (3,5)]}`

```
cartesian(@xs, @ys) =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else if isNil(tail(@xs))  
         then cons(createPair(head(@xs), head(@ys)),  
                   cartesian(@xs, tail(@ys)))  
         else ???
```



- But now, we can plug this term into the **red hole** and calculate its new output vector, and **we only need to evaluate its value on the third input**

`{[], Err, ?, ?}`

↓

`{[], Err, [(5,7), (5,8), (5,9)], ?}`

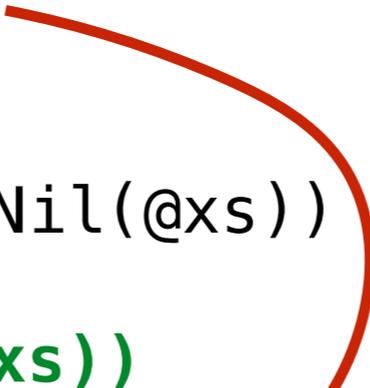
A match!

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], [1]), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{* , * , [(5,7), (5,8), (5,9)], [(2,4), (2,5), (3,4), (3,5)]}`

```
cartesian(@xs, @ys) =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else if isNil(tail(@xs))  
         then cons(createPair(head(@xs), head(@ys)),  
                   cartesian(@xs, tail(@ys)))  
         else ???
```



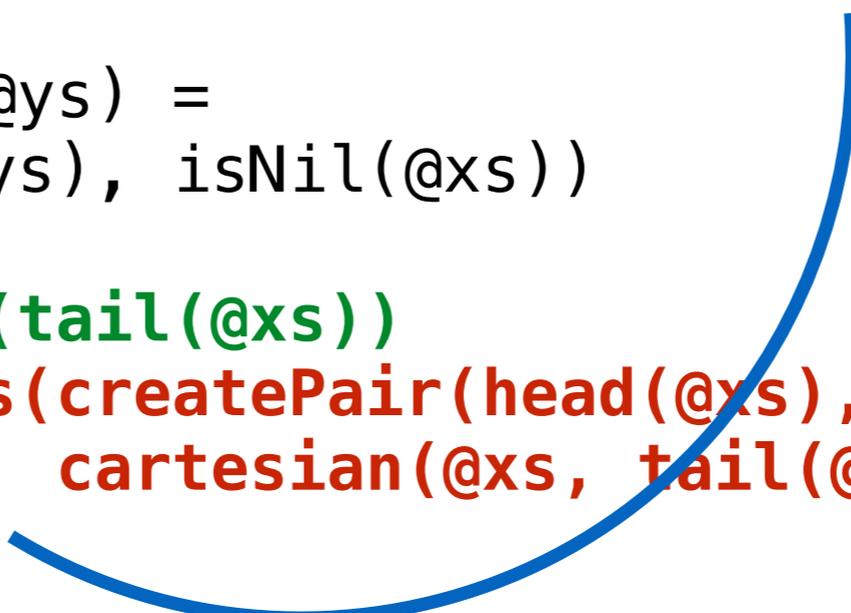
- But now, we can plug this term into the **red hole** and calculate its new output vector, and **we only need to evaluate its value on the third input**
- Note that because we are trying to find an ascending-recursive program, a correct term for the **red hole** can always successfully evaluate its value like we just saw!

Partial Evaluation

inputs: `{([], [2, 3, 4]), ([5], []), ([5], [7, 8, 9]), ([2, 3], [4, 5])}`

goal: `{* , * , [(5,7), (5,8), (5,9)], [(2,4), (2,5), (3,4), (3,5)]}`

```
cartesian(@xs, @ys) =  
  if or(isNil(@ys), isNil(@xs))  
  then nil()  
  else if isNil(tail(@xs))  
        then cons(createPair(head(@xs), head(@ys)),  
                  cartesian(@xs, tail(@ys)))  
  else ???
```



- Now we are only left with this blue hole and we can solve it recursively, thus finish the GGPA stage.

Benchmark (AscendRec)

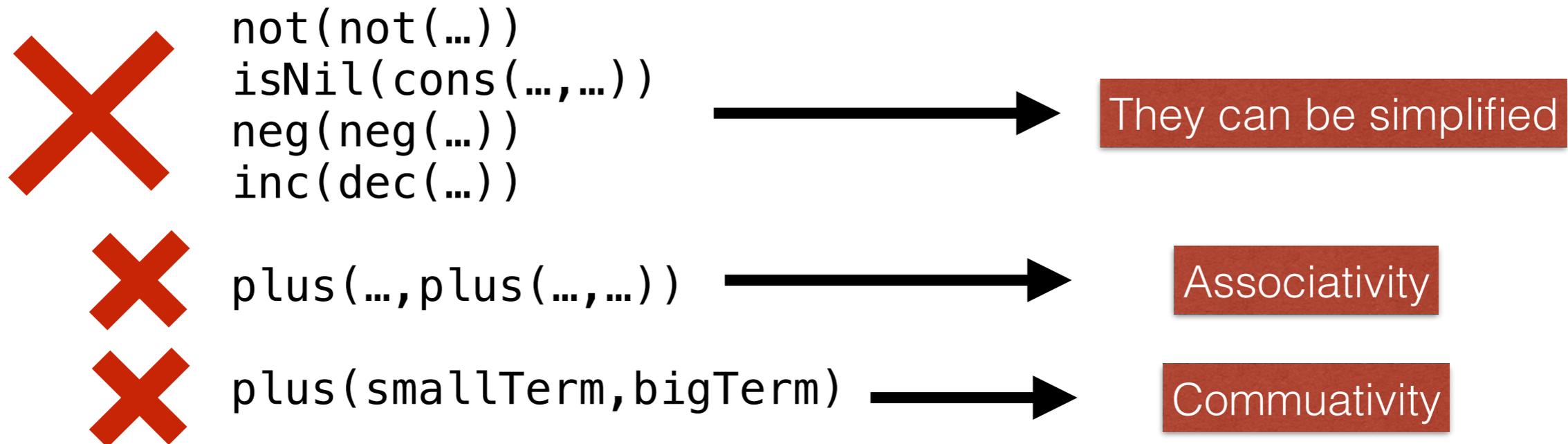
```
Summery:
```

name	cost	depth	examples	time
reverse	12	8	5	538.26ms
stutter	13	9	3	235.57ms
squareList	14	9	6	3,946.44ms
fib	15	8	8	2,575.98ms
insert	19	9	8	5,977.26ms
lastInList	14	5	5	7.77ms
shiftLeft	12	8	5	32.81ms
maxInList	20	10	7	12,844.99ms
flattenTree	14	10	3	79.12ms
sumUnder	10	5	5	7.83ms
times	11	6	6	319.75ms
contains	14	5	7	7.33ms
dropLast	15	6	5	11.93ms
evens	16	7	5	17.06ms
tConcat	15	11	6	48,338.31ms
cartesian	32	11	4	3,419.98ms
nodesAtLevel	27	11	12	241,406.70ms
Total	273	138	100	319.767s

We need much less examples now!

Limitations

- Because of the presence of ‘?’s, we can’t use **observational equivalence** for recursive terms. This can quickly lead to too many terms.
- To alleviate this problem, we can introduce some simple **term-rewriting check** to reject terms which can be rewritten into simpler ones:



Limitations

- For those programs that are not ascending-recursive, if we provide trace-complete examples (i.e. all recursive calls are included in the example set), the algorithm can synthesize it as if it was in ascending-recursive form.

```
dedup(@xs: List['0']): List['0'] =  
  if isNil(@xs)  
  then @xs  
  else if contains(tail(@xs), head(@xs))  
        then dedup(tail(@xs))  
        else cons(head(@xs), dedup(tail(@xs)))
```

- I'm still working on this algorithm. There might be more improvements in the future!

References

- Recursive Program Synthesis: <https://www.microsoft.com/en-us/research/publication/recursive-program-synthesis/>
- Escher-Scala on Github: <https://github.com/MrVPlusOne/Escher-Scala>
- Leon Online: <https://leon.epfl.ch>
- Flash Fill: <https://www.microsoft.com/en-us/research/video/programming-examples-pbe-flash-fill/>

That's all,
Thank You!

Any Questions?